Parameterisable spring-return actuator with emergency control function for adjusting dampers in technical building installations

- Air damper size up to approx. $4 \mathrm{~m}^{2}$
- Nominal torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating DC (0)2... 10 V Variable
- Position feedback DC 2... 10 V Variable


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 8.5 W |
|  | Power consumption in rest position | 3.5 W |
|  | Power consumption for wire sizing | 11 VA |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | Min. 20 Nm |
|  | Torque spring return | Min. 20 Nm |
|  | Positioning signal Y | DC $0 . . .10 \mathrm{~V}$ |
|  | Positioning signal Y note | Input impedance $100 \mathrm{k} \Omega$ |
|  | Control signal Y variable | Open-close |
|  |  | 3 -point (AC only) |
|  |  | Modulating (DC 0... 32 V ) |
|  | Operating range Y | DC 2... 10 V |
|  | Operating range Y variable | Start point DC $0.5 \ldots 30 \mathrm{~V}$ End point DC 2.5... 32 V |
|  | Position feedback U | DC $2 . .10 \mathrm{~V}$ |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point DC 0.5... 8 V |
|  |  | End point DC 2.5... 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | Selectable with switch L / R |
|  | Direction of motion variable | Electronically reversible |
|  | Direction of motion emergency control function | Selectable by mounting L / R |
|  | Manual override | By means of hand crank and locking switch |
|  | Angle of rotation | Max. $95^{\circ}$ |
|  | Angle of rotation note | adjustable starting at $33 \%$ in $2.5 \%$ steps (with mechanical end stop) |
|  | Running time motor | $150 \mathrm{~s} / 90^{\circ}$ |
|  | Motor running time variable | 70...220 s |
|  | Running time emergency control position | $<20 \mathrm{~s} / 90^{\circ}$ |
|  | Running time emergency setting position note | <20 s @ -20...50 ${ }^{\circ} \mathrm{C} /<60 \mathrm{~s}$ @ - $30^{\circ} \mathrm{C}$ |
|  | Adaption setting range | manual |
|  | Adaption setting range variable | No action <br> Adaption when switched on <br> Adaption after pushing the gear disengagement button |
|  | Override control | $\begin{aligned} & \text { MAX (maximum position) }=100 \% \\ & \text { MIN (minimum position) }=0 \% \\ & \text { ZS (intermediate position, AC only) }=50 \% \end{aligned}$ |
|  | Override control variable | $\begin{aligned} & \text { MAX }=(\text { MIN }+32 \%) . . .100 \% \\ & \text { MIN }=0 \% \ldots(\text { MAX }-32 \%) \\ & Z S=\text { MIN...MAX } \end{aligned}$ |
|  | Sound power level motor | 40 dB (A) |
|  | Spindle driver | Universal spindle clamp 10...25.4 mm |
|  | Position indication | Mechanical |

$\triangle$

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea)water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

| Mode of operation | The actuator moves the damper to the operating position at the same time as <br> tensioning the return spring. The damper is turned back to the emergency position by <br> spring force when the supply voltage is interrupted. |
| :--- | :--- |
| The actuator is connected with a standard modulating signal of DC $0 \ldots .10 \mathrm{~V}$ and drives |  |
| to the position defined by the positioning signal. Measuring voltage $U$ serves for the |  |
| electrical display of the damper position $0 . . .100 \%$ and as slave control signal for other |  |
| actuators. |  |$\quad$| The factory settings cover the most common applications. Single parameters can be |
| :--- |
| modified with the Belimo Service Tools MFT-P or ZTH EU. |


| Home position | The first time the supply voltage is switched on, i.e. at the time of commissioning, the <br> actuator carries out a synchronisation. The synchronisation is in the home position <br> (0\%). <br> The actuator then moves into the position defined by the positioning signal. |
| :--- | :--- |
| Adaption and synchronisation | An adaption can be triggered manually by pressing the "Adaption" button or with the <br> PC-Tool. Both mechanical end stops are detected during the adaption (entire setting <br> range). Automatic synchronisation after actuating the hand crank is programmed. The <br> synchronisation is in the home position (0\%). <br> The actuator then moves into the position defined by the positioning signal. <br> A range of settings can be adapted using the PC-Tool (see MFT-P documentation) |

Accessories

|  | Description | Type |
| :---: | :---: | :---: |
| Electrical accessories | Auxiliary switch, $2 \times$ SPDT | S2A-F |
|  | Feedback potentiometer, 200 Ohm, incl. installation accessories | P200A-F |
|  | Feedback potentiometer 1 kOhm, incl. installation accessories | P1000A-F |
|  | Signal converter voltage/current, supply AC/DC 24V | Z-UIC |
|  | Digital position indicator for front-panel mounting, 0...99\%, front mass $72 \times 72 \mathrm{~mm}$ | ZAD24 |
|  | Range controller for wall mounting, adjustable electron. Min./max. angle of rotation limitation | SBG24 |
|  | Positioner for wall mounting, range 0...100\% | SGA24 |
|  | Positioner in a conduit box, range 0...100\% | SGE24 |
|  | Positioner for front-panel mounting, range 0...100\% | SGF24 |
|  | Positioner for wall mounting, range 0...100\% | CRP24-B1 |
|  | Connecting cable $5 \mathrm{~m}, \mathrm{~A}+\mathrm{B}$ : RJ12 6/6, To ZTH/ZIP-USB-MP | ZK1-GEN |
|  | Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP | ZK2-GEN |
|  | Description | Type |
| Mechanical accessories | Shaft extension 250 mm , for damper spindles Ø $\varnothing$ 8... 25 mm | AV8-25 |
|  | End stop indicator for NF..A / SF..A | IND-AFB |
|  | Spindle clamp set for NF..A/SF..A (1", 3/4", 1/2") | K7-2 |
|  | Straight ball joint with M8, suitable for damper crank arms KH8 | KG10A |
|  | Angled ball joint with M8, suitable for damper crank arms KH8 | KG8 |
|  | Damper crank arm, for damper spindles | KH8 |
|  | Damper crank arm for NF..A / SF..A, for 3/4" spindles | KH-AFB |
|  | Form fit insert $10 \times 10 \mathrm{~mm}$, for spring return actuators NG | ZF10-NSA-F |
|  | Form fit insert $12 \times 12 \mathrm{~mm}$, for spring return actuators NG | ZF12-NSA-F |
|  | Form fit insert $16 \times 16 \mathrm{~mm}$, for spring return actuators NG | ZF16-NSA-F |
|  | Damper crank arm, for spring return actuators NG | ZG-AFB |
|  | Base plate extensions for NF..A/SF..A | Z-SF |
|  | Description | Type |
| Service Tools | Service Tool, for MF/MP/Modbus/LonWorks actuators and VAVController | ZTH EU |
|  | Belimo PC-Tool, software for adjustments and diagnostics | MFT-P |
|  | Adapter to Service Tool ZTH | MFT-C |

Notes $\quad$ - Connection via safety isolating transformer.

## Wiring diagrams

AC/DC 24 V , modulating


## Cable colours: <br> 1 = black <br> 2 = red <br> 3 = white <br> 5 = orange

## Functions

Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts


Override control with AC 24 V with rotary switch


Remote control $0 . . .100 \%$ with Minimum limit with positioner SG.. positioner SG..


Follow-up control (position-dependent)



Position indication



Caution:
The operating range must be set to DC 2... 10 V .
The $500 \Omega$ resistor converts the 4... 20 mA current signal to a voltage signal DC 2... 10 V


## Procedure

1. Connect 24 V to connections 1 and 2
2. Disconnect connection 3

- with direction of rotation 0 :

Actuator rotates to the left

- with direction of rotation 1 :

Actuator rotates to the right
3. Short-circuit connections 2 and 3:

- Actuator runs in opposite direction

Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

Override control and limiting with AC 24 V with relay contacts
Override control and limiting with AC 24 V with rotary switch


Control open-close


Control 3-point


Operating controls and indicators

(1) Membrane key and LED display green

Off: $\quad$ No power supply or malfunction
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode

## (2) Membrane key and LED display yellow

Off:
Standard mode
On: Adaptation and synchronising process active

Press button:
No function

## (3) Service plug

For connecting parameterisation and service tools

## Operating elements

The manual override, locking switch and direction of rotation switch elements are available on both sides

## Service

Service Tools connection
The actuator can be parameterised by ZTH EU via the service socket. For an extended parameterisation the PC tool can be connected.


## Dimensions [mm]

Spindle length


Clamping range

|  | OI | $\square \underline{\text { I }}$ | $\checkmark 1$ |
| :---: | :---: | :---: | :---: |
|  | 10... 22 | 10 | 14...25.4 |
|  | OI |  | $\square \underline{\text { I }}$ |
|  | 19...25.4 |  | 12... 18 |

Dimensional drawings


